

Taxonomization of Combinatorial Optimization Problems in Fourier Space

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Advisors: Leticia Hernando and Jose A. Lozano

Research area

Research area

- Optimization
- **Permutation-based** combinatorial optimization problems (COPs)

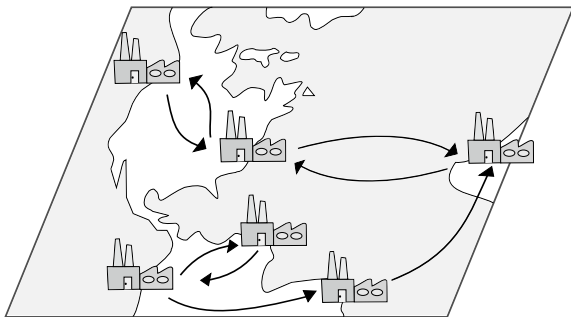
Permutation-based COPs

- Quadratic assignment problem (QAP)
- Linear ordering problem (LOP)
- Traveling salesman problem (TSP)

Quadratic Assignment Problem

Interpretation

A set of n facilities have to be assigned to n locations with the goal of minimizing the cost, which is a function of the flows and distances.



Source: <https://www.localsolver.com/docs/last/exampletour/qap.html>

Quadratic Assignment Problem

Interpretation

A set of n facilities have to be assigned to n locations with the goal of minimizing the cost, which is a function of the flows and distances.

Mathematical definition

Given a distance matrix $A = [a_{ij}]$ and a flow matrix $A' = [a'_{ij}]$, minimize the following objective function:

$$f(\sigma) = \sum_{i=1}^n \sum_{j=1}^n a_{\sigma(i)\sigma(j)} a'_{ij}.$$

Linear Ordering Problem

Interpretation

Given a matrix A , maximize the sum of the elements above the main diagonal when the rows and columns of A are jointly reordered.

Mathematical definition

Given a matrix $A = [a_{ij}]$, maximize the following objective function:

$$f(\sigma) = \sum_{i=1}^{n-1} \sum_{j=i+1}^n a_{\sigma(i)\sigma(j)}.$$

Linear Ordering Problem: example

	1	2	3
1	0	2	4
2	7	0	3
3	5	1	0

$f(\sigma) = 9$

	1	3	2
1	0	4	2
3	5	0	1
2	7	3	0

$f(\sigma) = 7$

	2	1	3
2	0	7	3
1	2	0	4
3	1	5	0

$f(\sigma) = 14$

	2	3	1
2	0	3	7
3	1	0	5
1	2	4	0

$f(\sigma) = 15$

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3	0	5	1
1	4	0	2
2	3	7	0

$f(\sigma) = 8$

	3	2	1
3	0	1	5
2	3	0	7
1	4	2	0

$f(\sigma) = 13$

Linear Ordering Problem

Mathematical definition

Given a matrix $A = [a_{ij}]$, maximize the following objective function:

$$f(\sigma) = \sum_{i=1}^{n-1} \sum_{j=i+1}^n a_{\sigma(i)\sigma(j)}.$$

Particular case of the QAP

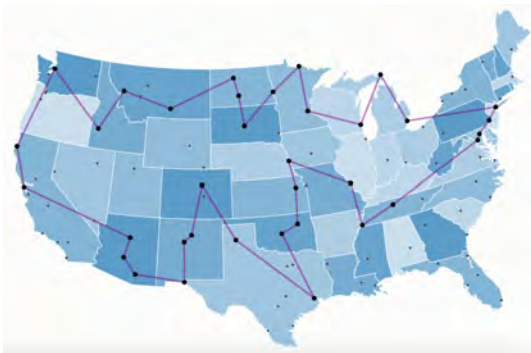
The LOP is a **particular case of the QAP** if

$$a'_{ij} = \begin{cases} 1 & \text{if } i < j \\ 0 & \text{otherwise} \end{cases}$$

Traveling Salesman Problem

Interpretation

Given n cities and the distances between them, find the shortest tour that passes exactly once through all of the cities.



Source: <https://blog.essaycorp.com/travelling-salesman-problem/>

Traveling Salesman Problem

Interpretation

Given n cities and the distances between them, find the shortest tour that passes exactly once through all of the cities.

Mathematical definition

Given a distance matrix $A = [a_{ij}]$, minimize the following objective function:

$$f(\sigma) = a_{\sigma(n)\sigma(1)} + \sum_{i=1}^{n-1} a_{\sigma(i)\sigma(i+1)}.$$

Traveling Salesman Problem

Mathematical definition

Given a distance matrix $A = [a_{ij}]$, minimize the following objective function:

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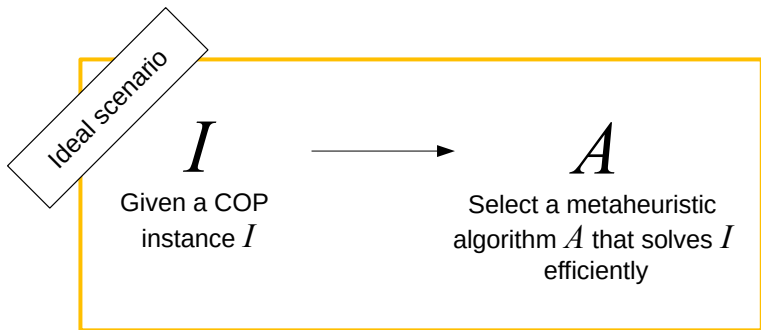
Particular case of the QAP

The TSP is a **particular case of the QAP** if

$$a'_{ij} = \begin{cases} 1 & \text{if } j = i + 1 \text{ or } (i = n \text{ and } j = 1) \\ 0 & \text{otherwise} \end{cases}$$

Ideal scenario

The behaviour of metaheuristic algorithms varies from problem to problem and even from instance to instance

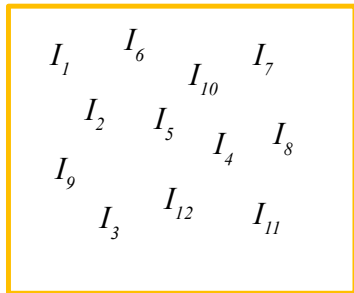


- Given a problem, tell me the **best** algorithm for it!
- Given an **instance** of a problem, tell me the best algorithm for it!

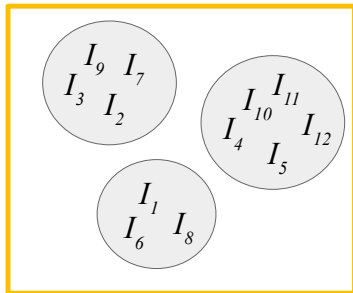
Taxonomy

Final objective

Problem instances



Taxonomy



Instances that can be solved efficiently by the same algorithms are grouped together

Initial questions and motivation

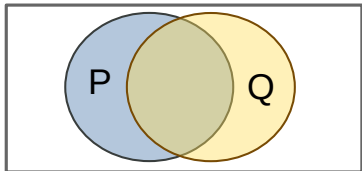
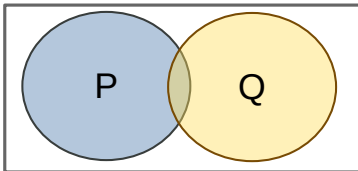
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- Example:
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- Is there a tool for comparing instances coming from different problems easily?
- We would like to look for properties that affect the behaviour of algorithms and that are shared by instances of different problems.
- Example: intersection between problems (in terms of objective functions).
- Is there a framework that puts instances of different problems in the same terms?

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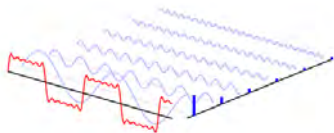
- Is there a tool for comparing instances coming from different problems easily?
- We would like to look for properties that affect the behaviour of algorithms and that are shared by instances of different problems.
- Example: intersection between problems (in terms of objective functions).
- Is there a framework that puts instances of different problems in the same terms?

SOLUTION: USE THE FOURIER TRANSFORM

Classic Fourier transform

Fourier coefficients

$$\begin{cases} a_0 = \frac{1}{L} \int_{-L}^L f(x) dx \\ a_n = \frac{1}{L} \int_{-L}^L f(x) \cos\left(\frac{n\pi x}{L}\right) dx \\ b_n = \frac{1}{L} \int_{-L}^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \end{cases}$$



Source:

<https://pgfplots.net/fourier-transform/>

Decomposition of f

$$f(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos\left(\frac{n\pi x}{L}\right) + \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right)$$

Fourier transform over the symmetric group

Base functions

Irreducible representations of the symmetric group.

- Matrix-valued functions.
- The number of irreducible representations of Σ_n is the number of partitions of n .

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Partition of n

A partition of a number n is a tuple that sums to n .

Example ($n = 5$)

Partitions of 5:

(5), (4, 1), (3, 2), (3, 1, 1), (2, 2, 1), (2, 1, 1, 1), (1, 1, 1, 1, 1).

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Example ($n = 5$)

Irreducible representations of Σ_5 :

$$\rho(5), \rho(4,1), \rho(3,2), \rho(3,1,1), \rho(2,2,1), \rho(2,1,1,1), \rho(1,1,1,1,1).$$

Fourier transform over the symmetric group

Base functions

Irreducible representations of the symmetric group.

- **Matrix-valued** functions.
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Example: $\rho_{(n)}$

$\rho_{(n)} : \Sigma_n \longrightarrow \mathbb{R}^{1 \times 1}$ is the constant function $\rho_{(n)}(\sigma) = (1)$.

Fourier transform over the symmetric group

Base functions

Irreducible representations of the symmetric group.

- **Matrix-valued** functions.
- The number of irreducible representations of Σ_n is the number of partitions of n .

Example: $\rho_{(2,1)}$

$$\rho_{(2,1)}(1, 2, 3) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\rho_{(2,1)}(1, 3, 2) = \begin{bmatrix} 1/2 & \sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{bmatrix}$$

$$\rho_{(2,1)}(2, 1, 3) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\rho_{(2,1)}(2, 3, 1) = \begin{bmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{bmatrix}$$

$$\rho_{(2,1)}(3, 1, 2) = \begin{bmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix}$$

$$\rho_{(2,1)}(3, 2, 1) = \begin{bmatrix} 1/2 & -\sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix}$$

Fourier transform over the symmetric group

Fourier coefficients

Given a function $f : \Sigma_n \rightarrow \mathbb{R}$, the Fourier coefficient associated with partition λ is:

$$\hat{f}_\lambda = \sum_{\sigma} f(\sigma) \cdot \rho_\lambda(\sigma).$$

The collection of all Fourier coefficients is the Fourier transform of f .

Fourier transform over the symmetric group

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Fourier inversion theorem

$$f(\sigma) = \frac{1}{|\Sigma_n|} \sum_{\lambda} d_{\rho_\lambda} \text{Tr}[\hat{f}_\lambda \cdot \rho_\lambda(\sigma)]$$

Fourier transform over the symmetric group

Interpretation

Coefficient $\hat{f}_{(n)}$

$$\hat{f}_{(n)} = \sum_{\sigma} f(\sigma).$$

Directly related to the mean value of f .

Other coefficients

If $f = p$ (probability),

- $\hat{p}_{(n-1,1)}$ captures information about first order marginals:
 $p(\sigma : \sigma(i) = j)$.
- \hat{p}_{λ} ($\lambda \neq (n), (n-1, 1)$) captures information about higher order marginals.

Characterization of the LOP

Example

	1	2	3
1	0	2	4
2	7	0	3
3	5	1	0

$$f(\sigma) = 9$$

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$$f(\sigma) = 13$$

Fitness function:

$$f(1, 2, 3) = 9$$

$$f(1, 3, 2) = 7$$

$$f(2, 1, 3) = 14$$

$$f(2, 3, 1) = 15$$

$$f(3, 1, 2) = 8$$

$$f(3, 2, 1) = 13$$

Fourier transform (alternative representation of f):

$$\hat{f}_{(3)} \approx (66)$$

$$\hat{f}_{(2,1)} \approx \begin{pmatrix} -6.5 & -11.3 \\ 0.9 & 1.5 \end{pmatrix}$$

$$\hat{f}_{(1,1,1)} \approx (-2).$$

Characterization of the LOP

Structure for low dimensions

Structure of the example

$\hat{f}_{(3)}$ and $\hat{f}_{(1,1,1)}$ are arbitrary, while

$$\hat{f}_{(2,1)} \approx \begin{pmatrix} -6.5 & -11.3 \\ 0.9 & 1.5 \end{pmatrix} \approx \begin{pmatrix} -6.5 & \sqrt{3} \cdot (-6.5) \\ 0.9 & \sqrt{3} \cdot 0.5 \end{pmatrix}.$$

Structure when $n = 3$

$\hat{f}_{(3)}$ and $\hat{f}_{(1,1,1)}$ are arbitrary, while

$$\hat{f}_{(2,1)} = \begin{bmatrix} | & | \\ \mathbf{x} & \sqrt{3}\mathbf{x} \\ | & | \end{bmatrix}$$

Characterization of the LOP

Structure for low dimensions

Structure when $n = 4$

- $\hat{f}_{(4)}$ is arbitrary
- $\hat{f}_{(3,1)}$ and $\hat{f}_{(2,1,1)}$ are rank-1:

$$\hat{f}_{(3,1)} = \begin{bmatrix} | & | & | \\ \mathbf{x} & \sqrt{3}\mathbf{x} & \sqrt{6}\mathbf{x} \\ | & | & | \end{bmatrix}$$

$$\hat{f}_{(2,1,1)} = \begin{bmatrix} | & | & | \\ \sqrt{2}\mathbf{y} & \mathbf{y} & \sqrt{3}\mathbf{y} \\ | & | & | \end{bmatrix}$$

- $\hat{f}_{(2,2)}, \hat{f}_{(1,1,1,1)} = 0$

Characterization of the LOP

Theorem

Theorem

If $f : \Sigma_n \rightarrow \mathbb{R}$ is the objective function of an LOP instance, then its FT has the following properties:

- 1** $\hat{f}_\lambda = 0$, if $\lambda \neq (n), (n-1, 1), (n-2, 1, 1)$.
- 2** \hat{f}_λ has at most rank one for $\lambda = (n-1, 1), (n-2, 1, 1)$.
Having rank one is equivalent to the fact that the matrix columns are proportional.
- 3** For $\lambda = (n-1, 1), (n-2, 1, 1)$ and a fixed dimension n , the proportions among the columns of \hat{f}_λ are the same for all the instances.

Characterization of the LOP

Reciprocal implication

Theorem

If f is an LOP function with non-null $(n-1, 1)$ and $(n-2, 1, 1)$ Fourier coefficients, and a function g satisfies the conditions mentioned in the previous theorem, that is,

- 1** $\hat{g}_\lambda = 0$, for $\lambda \neq (n), (n-1, 1), (n-2, 1, 1)$.
- 2** $\hat{g}_{(n-1,1)}$ is 0 or rank-one with the same column proportions as $\hat{f}_{(n-1,1)}$.
- 3** $\hat{g}_{(n-2,1,1)}$ is 0 or rank-one with the same column proportions as $\hat{f}_{(n-2,1,1)}$.

Then, g is the objective function of an LOP instance.

Characterization of the LOP

Proportions of coefficient $(n-1, 1)$

$$\left[\begin{array}{ccccccc} * & * & * & \dots & * & * & \end{array} \right]$$

$\cdot\sqrt{3}$

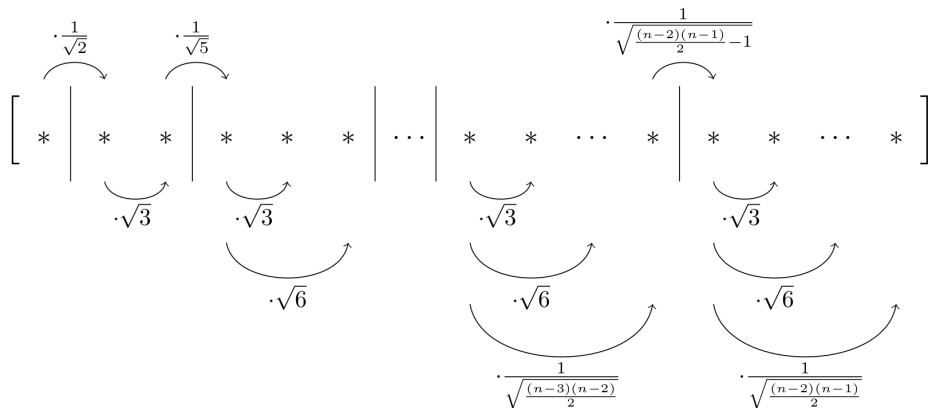
$\cdot\sqrt{6}$

$\cdot\sqrt{\frac{(n-2)(n-1)}{2}}$

$\cdot\sqrt{\frac{(n-1)n}{2}}$

Characterization of the LOP

Proportions of coefficient $(n - 2, 1, 1)$



Characterization of the TSP

Structure for low dimensions

Structure when $n = 4$

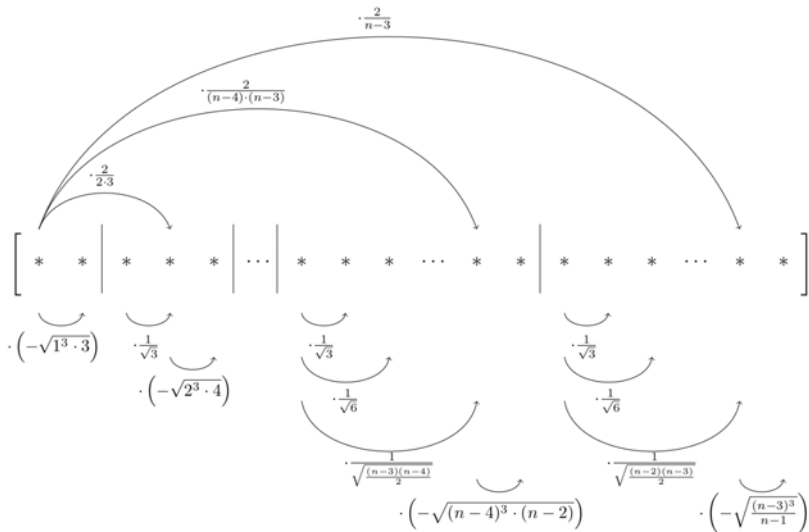
- $\hat{f}_{(4)}$ is arbitrary.
- $\hat{f}_{(2,2)}$ and $\hat{f}_{(2,1,1)}$ are rank-1:

$$\hat{f}_{(2,2)} = \begin{bmatrix} | & | \\ \mathbf{x} & -\frac{1}{\sqrt{3}}\mathbf{x} \\ | & | \end{bmatrix} \quad \hat{f}_{(2,1,1)} = \begin{bmatrix} | & | & | \\ \mathbf{y} & \sqrt{\frac{1}{2}}\mathbf{y} & \sqrt{\frac{3}{2}}\mathbf{y} \\ | & | & | \end{bmatrix}$$

- $\hat{f}_{(3,1)}, \hat{f}_{(1,1,1,1)} = 0$.
- If the TSP is symmetric, $\hat{f}_{(2,1,1)} = 0$.

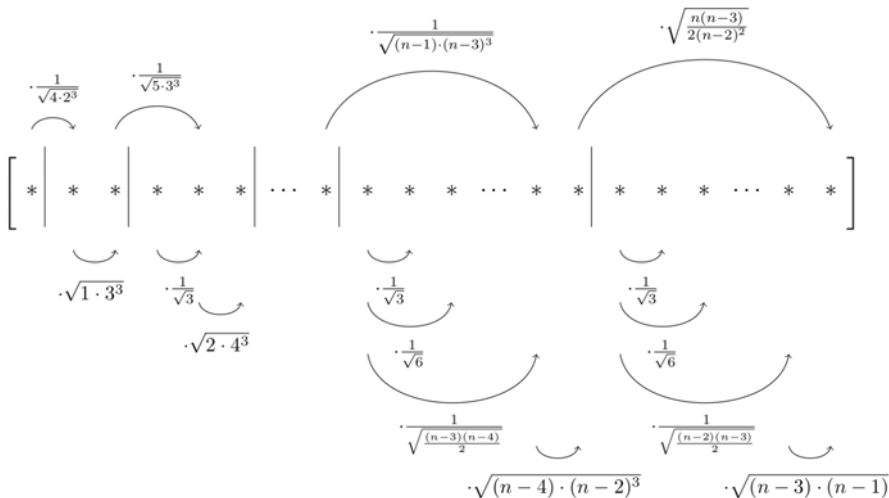
Characterization of the TSP

Proportions of coefficient $(n - 2, 2)$



Characterization of the TSP

Proportions of coefficient $(n - 2, 1, 1)$



Characterization of the QAP

Theorem

If $f : \Sigma_n \rightarrow \mathbb{R}$ is the objective function of a QAP instance, then its FT has the following properties:

- 1** $\hat{f}_\lambda = 0$, if $\lambda \neq (n), (n-1, 1), (n-2, 2), (n-2, 1, 1)$.
- 2** \hat{f}_λ has at most rank one for $\lambda = (n-2, 2), (n-2, 1, 1)$.
- 3** \hat{f}_λ has at most rank two for $\lambda = (n-1, 1)$.

- The reciprocal is also true (proved).

Characterizations: summary

Non-zero Fourier coefficients when $n = 5$:

COPs	Fourier coefficients						
	(5)	(4, 1)	(3,2)	(3,1,1)	(2,2,1)	(2,1,1,1)	(1,1,1,1,1)
LOP	✓	✓		✓			
STSP	✓		✓				
TSP	✓		✓	✓			
QAP	✓	✓	✓	✓			

- As n grows, the number of Fourier coefficients grows, but these problems still have at most 4 non-zero coefficients.

Consequences of the characterizations

Intrinsic dimensions of the problems

Number of parameters needed to define the different problems:

COP	Usual representation	Fourier representation
LOP	$n^2 - n$	$\frac{n^2 - n}{2} + 1$
TSP	$n(n - 1)$	$(n - 1)(n - 2)$
STSP	$\frac{n(n-1)}{2}$	$\frac{(n-1)(n-2)}{2}$
QAP	$2(n^2 - n)$	$2(n^2 - n) - 7$

Consequences of the characterizations

Intersections between problems

Consider a COP as a set of objective functions, then:

- The intersection between the LOP and the symmetric TSP is the set of constant functions.

COPs	Fourier coefficients						
	(n)	$(n-1, 1)$	$(n-2, 2)$	$(n-2, 1, 1)$	$(n-2, 2, 1)$	\dots	$(1, 1, \dots, 1)$
LOP	✓	✓		✓			
STSP	✓		✓				

Consequences of the characterizations

Intersections between problems

Consider a COP as a set of objective functions, then:

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- The intersection between the LOP and the TSP is the set of constant functions.

COPs	Fourier coefficients						
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LOP	✓	✓		✓			
TSP	✓		✓	✓			

Consequences of the characterizations

Intersections between problems

Consider a COP as a set of objective functions, then:

- The intersection between the LOP and the symmetric TSP is the set of constant functions.
- The intersection between the LOP and the TSP is the set of constant functions.
- The intersection between the LOP/(symmetric)TSP and the QAP is the LOP/(symmetric)TSP.

Breaking down the LOP

Consider the problem composed by those objective functions with a given coefficient equal to 0.

What happens if coefficient $(n - 2, 1, 1)$ is 0?

- The problem is P (proved)
- We implemented a polynomial algorithm

What happens if coefficient $(n - 1, 1)$ is 0?

The problem is NP-hard (proved)

Conclusion

Many interesting open questions:

- Which is the minimal Fourier representation for a problem to be NP-hard?

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- Other problems?

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- Which is the minimal Fourier representation for a problem to be NP-hard?
- The intersection of problems is trivial, but what happens with rankings?
- Relation between the Fourier decomposition and elementary lanscape decomposition?
- Other problems?
- Taxonomy

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